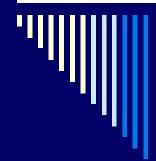


Efficient algorithms for Steiner Tree Problem

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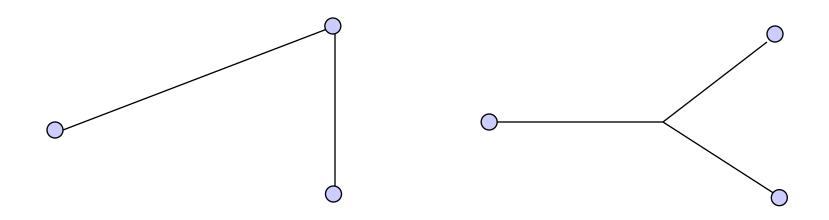


- □ The Steiner Problem in Graphs,
 - by S.E.Dreyfus and R.A. Wagner, Networks, 1972
- A Faster Algorithm for the Steiner Tree Problem,
 - By D. Molle, S. Richter and P.Rossmanith, STACS06, 2006

- Given a weighted graph G=(V, E, ω), weight on edges, and a steiner set $S \subseteq V$;
- A <u>steiner graph</u> of S is a connected subgraph of G which contains all nodes in S;
- The Steiner Tree problem is to find a steiner graph of S with minimum weight.
- This problem is quite important in industrial applications.

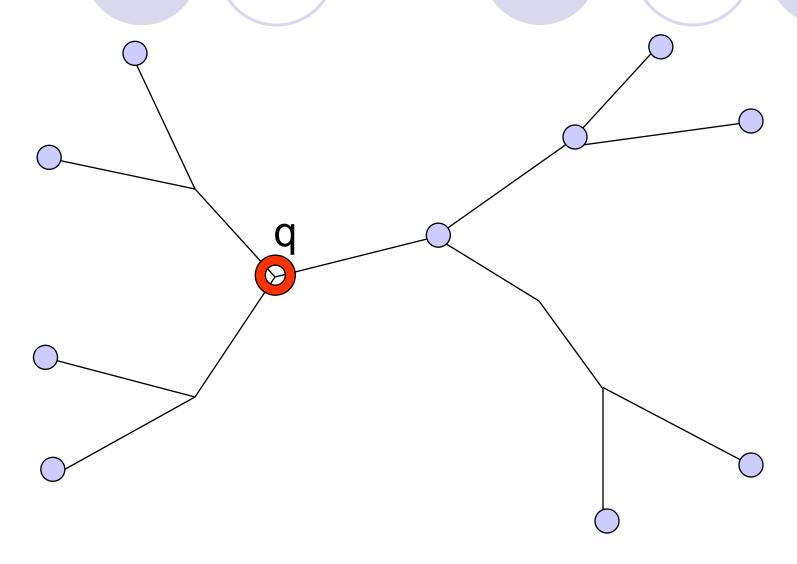
- The Steiner Tree problem is NP-Complete(By Karp, 1971).
- Approximatable within 1.55 ratio, but APXcomplete.
- Solvable in $O(3^k n^2)$ Improved up to $(2+\delta)^k n^{O(\frac{1}{\delta} \ln \frac{1}{\delta})}$

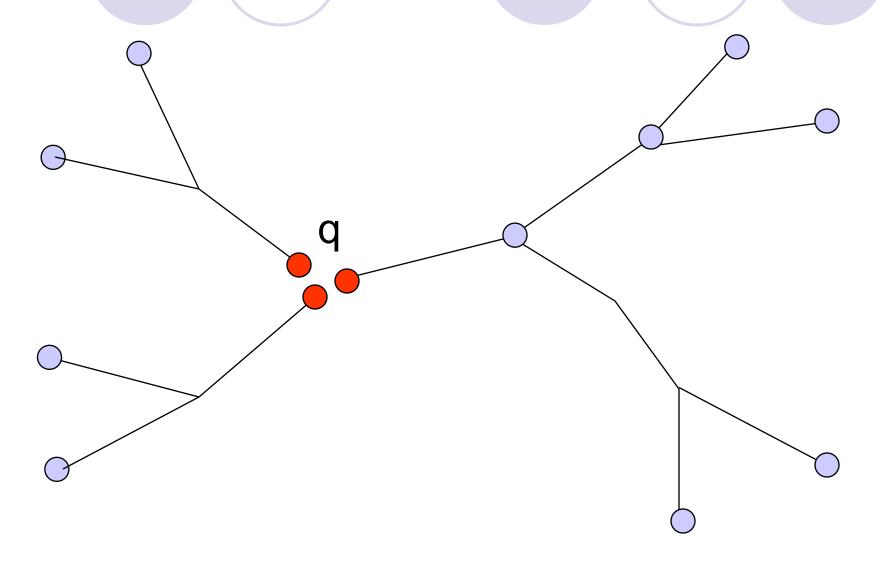
Why Steiner Tree problem is Hard?

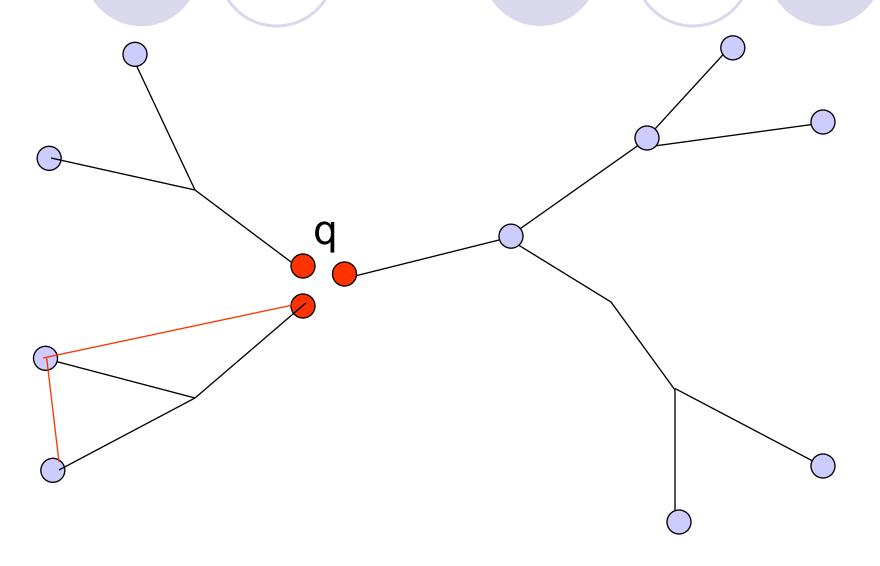


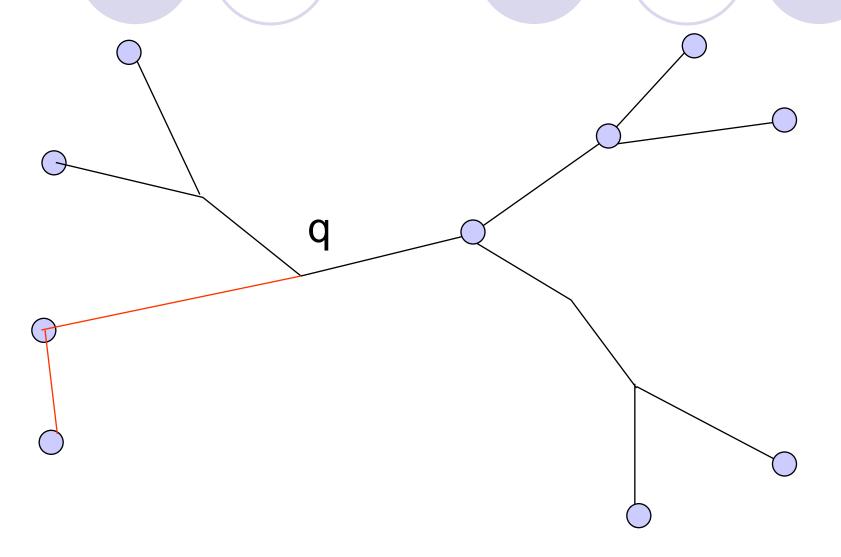
Spanning Tree VS. Steiner Tree

- Theorem: Let T be an optimal steiner tree for S, q be an inner node in T; If we break down T into several subtrees $T_1, T_2 \dots$ in q, T_i are optimal for $V(T_i) \cap S + q$
- This can be proved by contradiction.







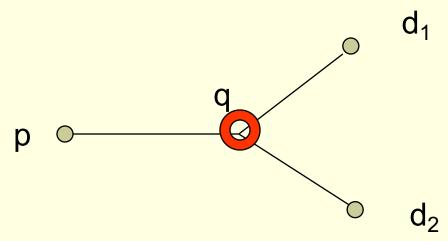


Two Phrases:

- Computing the optimal steiner trees containing D and p, where $D \subseteq S, p \in V$;
- Computing the optimal steiner tree for S;
- Let *OPT(D, p)* denote the optimal steiner tree for D and p, *SP(u, v)* denote the shortest path between u and v in G;

- Computing the optimal steiner trees for D and p;
- If |D| < 3, w.l.o.g. let $D = \{d_1, d_2\}$, so

$$OPT(D, p) = \min_{q \in V} \{SP(d_1, q) + SP(d_2, q) + SP(p, q)\}$$



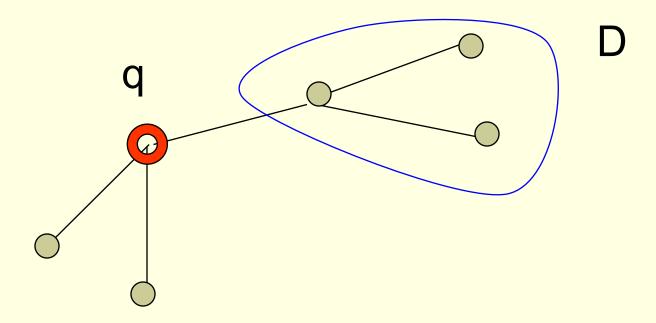
- Computing the optimal steiner trees for D and p;
 - If $|D| \ge 3$, then

$$OPT(D, p) = \min_{q \in V, E \subseteq D} \{SP(p, q) + OPT(E, q) + OPT(D - E, q)\}$$

$$p \qquad q$$

Computing the optimal steiner tree for S;

$$OPT(S) = \min_{q \in V, D \subseteq S} \{OPT(D, q) + OPT(S - D, q)\}$$



Time Complexity:

Phrase 1, time=
$$\sum_{i=3}^{k} {k \choose i} 2^{i} n^{2} \leq 3^{k} n^{2}$$

- Phrase 2, time= $2^k n^2$
- Total Dreyfus-Wagner's algorithm takes time $O(3^k n^2)$.

- The most time-consume part of Dreyfus-Wagner algorithm is phrase
 1, we have to enumerate all possible subsets of every subset of S;
- Can we reduce the cost of this part?

- Break down the optimal steiner tree only in steiner node;
- Enumerate subset only of size <t;</p>





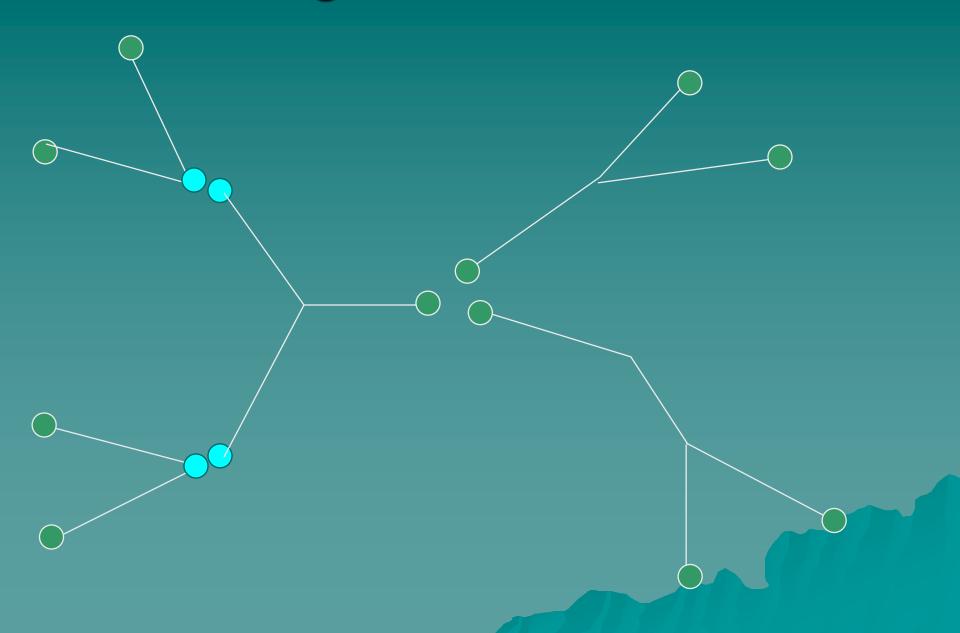
For all subset D of S:

$$OPT(D) = \min_{\substack{E \subseteq D, |E| \le t \\ q \in D}} \{OPT(E) + OPT(D - E + q)\}$$

In some cases, this procedure may fail, simply because all steiner nodes have already become leaves, and the tree is still not small enough.

Extend the steiner set





Lemma Let T be an optimal steiner tree for S, t is an integer, we can add at most |S|/(t-1) many non-steiner nodes into S such that T can be divided into several subtrees of size no larger than t, and all nodes in S are leaves in those subtree.

- ◆ Let t= c |S|;
- Enumerate all possible subset of V of size |S|/(t-1), add this set into S;
- ◆ For all subsets D of S of size less than t, call Dreyfus-Wagner algorithm to compute the optimal steiner tree for D;
- For all subsets D of S of size no less than t, $OPT(D) = \min_{E \subseteq D, |E| \le t} \{OPT(E) + OPT(D E + q)\}$

The running time of this algorithm is

$$(2+\delta)^k n^{O(\frac{1}{\delta}\ln\frac{1}{\delta})}$$

Question?